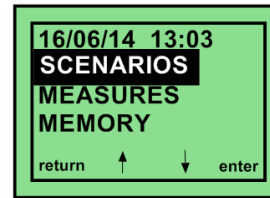
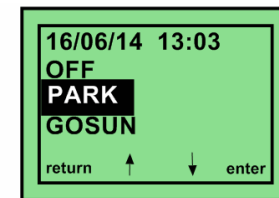


# THE FOLLOWING MUST BE DONE WITH AUTO TURNED OFF

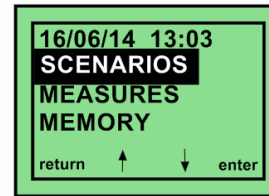
1. Perform a **“PARK”** scenario in the control box menu. The robot will find its home position and the collimator should point down.



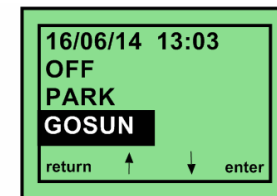
Select SCENARIOS then PARK and validate with the green button



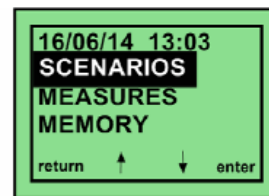
2. Perform a **“GOSUN”** scenario in the control box menu. The sensor head will point to the sun.



Select SCENARIOS then GOSUN and validate with the green button



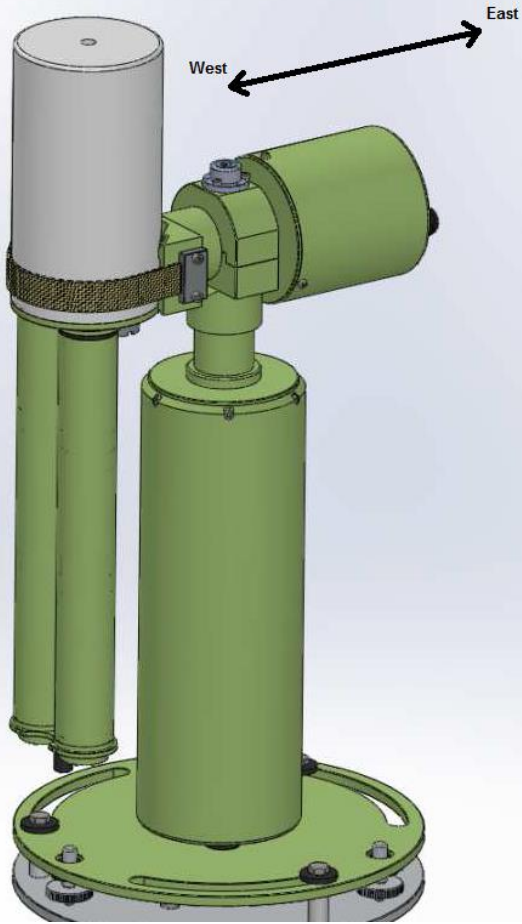
3. Perform a **“TRACK SUN”** scenario in the Control box menu, The robot will follow the sun. Check that the sun spot is centered on the collimator target at the end of the scenario.



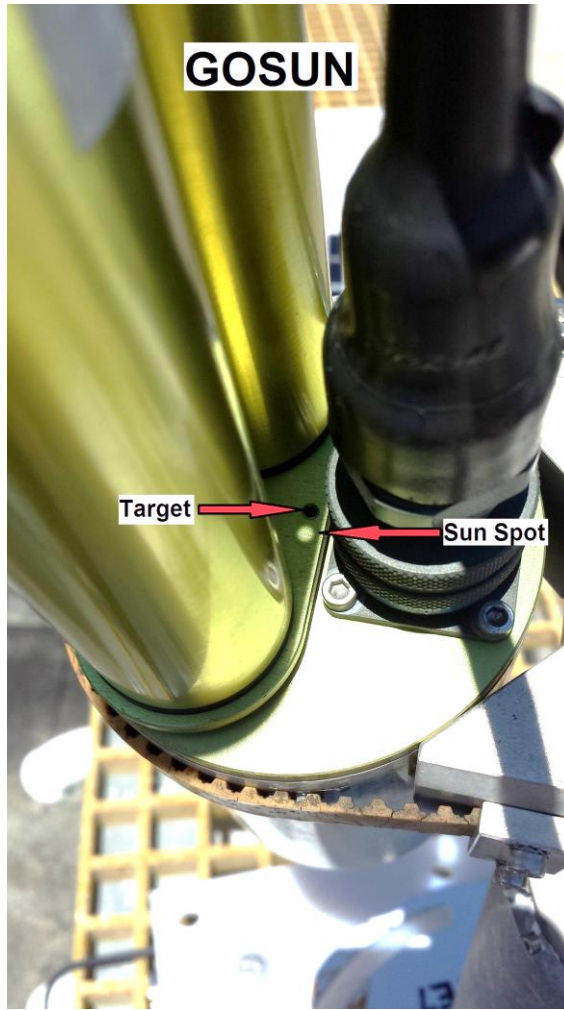
Select SCENARIOS then TRACK SUN and validate with the green button



# PARK



# GOSUN



# TRACK

